Scheme & Syllabus of

UNDERGRADUATE DEGREE COURSE

B.Tech. VII & VIII Semester

Electrical and Electronics Engineering



Rajasthan Technical University, Kota Effective from session: 2020 – 2021



Scheme & Syllabus

IV Year- VII & VIII Semester: B. Tech. (Electrical and Electronics Engineering)

Teaching & Examination Scheme B.Tech.: Electrical and Electronics Engineering 4th Year - VII Semester

| SN | Category | | Course | Hours per Week | | | | | | Cr | |
|----|----------|---------|---|-------------------|----|---|------------|-----|---------|-------|-----|
| | omesge:y | Code | Name | L | т | P | Exm Hrs | IA | ET E | Total | |
| 1 | | 7EX5-11 | Digital Signal Processing. | | | | | | | | |
| 2 | PEC | 7EX5-12 | Digital Control System. | 3 | 0 | 0 | 3 | 30 | 120 | 150 | 3 |
| 3 | | 7EX5-13 | Image Processing and Pattern Recognitation | | | | _ | | | | |
| 4 | OE | | Open Elective-I | 3 | 0 | 0 | 3 | 30 | 120 | 150 | 3 |
| | | | Sub total | 6 | 0 | 0 | | 60 | 240 | 300 | 6 |
| | | | PRACTICAL & SESS | ION | AL | | | | | | |
| 5 | PCC | 7EX4-21 | DBMS Lab | 0 | 0 | 4 | 2 | 60 | 40 | 100 | 2 |
| 6 | PCC | 7EX4-22 | Advanced Control System Lab | 0 | 0 | 4 | 2 | 60 | 40 | 100 | 2 |
| 7 | PSIT | 7EX7-30 | Industrial Training | 1 | 0 | 0 | | 75 | 50 | 125 | 2.5 |
| 8 | | 7EX7-40 | Seminar | 2 | 0 | 0 | | 60 | 40 | 100 | 2 |
| 9 | SODECA | 7EX8-00 | Social Outreach, Discipline & Extra Curricular Activities | 0 | 0 | 0 | | | 25 | 25 | 0.5 |
| | | | Sub total | 3 | 0 | 8 | | 255 | 195 | 450 | 9 |
| | | | TOTAL of VII SEMESTER | 9 | 0 | 8 | | 315 | 435 | 750 | 15 |

L: Lecture, T: Tutorial, P: Practical, Cr: Credits ETE: End Term Exam, IA: Internal Assessment



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IV Year- VII & VIII Semester: B. Tech. (Electrical and Electronics Engineering)

Teaching & Examination Scheme B.Tech.: Electrical and Electronics Engineering 4th Year - VIII Semester

| SN | Category | | Course | Hours per Week | | | | | | | Cr |
|----|----------|---------|--|-------------------|-----|---|------------|-----|-----|-------|------|
| | | Code | Name | L | т | P | Exm Hrs | IA | ЕТЕ | Total | |
| 1 | PCC | 8EX4-01 | Digital Communication and Information Theory | 3 | 0 | 0 | 3 | 30 | 120 | 150 | 3 |
| 2 | OE | | Open Elective-II | 3 | 0 | 0 | 3 | 30 | 120 | 150 | 3 |
| | | | Sub Total | 6 | 0 | 0 | | 60 | 240 | 300 | 6 |
| | | | PRACTICAL & SESS | ION | IAL | | | | | | |
| 3 | PCC | 8EX4-21 | Embedded Systems Lab | 0 | 0 | 4 | | 60 | 40 | 100 | 2 |
| 6 | Project | 8EX7-50 | Project | 3 | 0 | 0 | | 210 | 140 | 350 | 7 |
| 7 | SODECA | 8EX8-00 | SODECA | 0 | 0 | 0 | | 0 | 25 | 25 | 0.5 |
| | | | Total | 3 | 0 | 4 | | 270 | 205 | 475 | 9.5 |
| _ | | | TOTAL of VII SEMESTER | 9 | 0 | 4 | | 330 | 445 | 775 | 15.5 |

L: Lecture, T: Tutorial, P: Practical, Cr: Credits ETE: End Term Exam, IA: Internal Assessment



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IV Year- VII & VIII Semester: B. Tech. (Electrical and Electronics Engineering)

| List of | List of Open Electives for Electrical and Electronics Engineering | | | | | | | |
|-----------------|---|-----------------|---|--|--|--|--|--|
| Subject Code | Title | Subject Code | Title | | | | | |
| | Open Elective - I | 3000 | Open Elective - II | | | | | |
| 7AG6-60.1 | Human Engineering and Safety | 8AG6-60.1 | Energy Management | | | | | |
| 7AG6-60.2 | Environmental Engineering and Disaster Management | 8AG6-60.2 | Waste and By-product Utiliza- tion | | | | | |
| 7AN6-60.1 | Aircraft Avionic System | 8AN6-60.1 | Finite Element Methods | | | | | |
| 7AN6-60.2 | Non-Destructive Testing | 8AN6-60.2 | Factor of Human Interactions | | | | | |
| 7CH6-60.1 | Optimization Techniques | 8CH6-60.1 | Refinery Engineering Design | | | | | |
| 7CH6-60.2 | Sustainable Engineering | 8CH6-60.2 | Fertilizer Technology | | | | | |
| 7CR6-60.1 | Introduction to Ceramic Science & Technology | 8CR6-60.1 | Electrical and Electronic Ceramics | | | | | |
| 7CR6-60.2 | Plant, Equipment and Furnace Design | 8CR6-60.2 | Biomaterials | | | | | |
| 7CE6-60.1 | Environmental Impact Analysis | 8CE6-60.1 | Composite Materials | | | | | |
| 7CE6-60.2 | Disaster Management | 8CE6-60.2 | Fire and Safety Engineering | | | | | |
| 7CS6-60.1 | Quality Management/ISO 9000 | 8CS6-60.1 | Big Data Analytics | | | | | |
| 7CS6-60.2 | Cyber Security | 8CS6-60.2 | IPR, Copyright and Cyber Law of India | | | | | |
| 7EC6-60.1 | Principle of Electronic communication | 8EC6-60.1 | Industrial and Biomedical applications of RF Energy | | | | | |
| 7EC6-60.2 | Micro and Smart System Technology | 8EC6-60.2 | Robotics and control | | | | | |
| 7ME6-60.1 | Finite Element Analysis | 8ME6-60.1 | Operations Research | | | | | |
| 7ME6-60.2 | Quality Management | 8ME6-60.2 | Simulation Modeling and Analysis | | | | | |
| 7MI6-60.1 | Rock Engineering | 8MI6-60.1 | Experimental Stress Analysis | | | | | |
| 7MI6-60.2 | Mineral Processing | 8MI6-60.2 | Maintenance Management | | | | | |
| 7PE6-60.1 | Pipeline Engineering | 8PE6-60.1 | Unconventional Hydrocarbon Resources | | | | | |
| 7PE6-60.2 | Water Pollution control Engineering | 8PE6-60.2 | Energy Management & Policy | | | | | |
| 7TT6-60.1 | Technical Textiles | 8TT6-60.1 | Material and Human Resource Management | | | | | |
| 7TT6-60.2 | Garment Manufacturing Technology | 8TT6-60.2 | Disaster Management | | | | | |



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7EX5-11: DIGITAL SIGNAL PROCESSING

Credit: 3 Max. Marks: 150(IA:30, ETE:120)
3L+0T+0P End Term Exam: 3 Hours

| SN | CONTENTS | Hours |
|----|--|-------|
| 1 | Introduction: Objective, scope and outcome of the course. | 1 |
| 2 | Discrete-time signals and systems | 80 |
| | Discrete time signals and systems: Sequences; representation of sig- | |
| | nals on orthogonal basis; Representation of discrete systems using | |
| | difference equations, Samplingand reconstruction of signals - aliasing; | |
| | Sampling theorem and Nyquist rate | |
| 3 | Z-transform | 06 |
| | z-Transform, Region of Convergence, Analysis of Linear Shift Invariant | |
| | systems using ztransform, Properties of z-transform for causal sig- | |
| | nals, Interpretation of stability in z-domain, Inverse z-transforms. | |
| 4 | Discrete Fourier Transform | 10 |
| | Frequency Domain Analysis, Discrete Fourier Transform (DFT), Prop- | |
| | erties of DFT, | |
| | Connvolution of signals, Fast Fourier Transform Algorithm, Parseval's | |
| | Identity, | |
| | Implementation of Discrete Time Systems | |
| 5 | Design of Digital filters | 11 |
| | Design of FIR Digital filters: Window method, Park-McClellan's me- | |
| | thod. Design of IIR Digital Filters: Butterworth, Chebyshev and Elliptic | |
| | Approximations; Low-pass, Band-pass, Bandstop and High-pass fil- | |
| | ters. | |
| | Effect of finite register length in FIR filter design. Parametric and non- | |
| | parametric spectral estimation. Introduction to multi-rate signal | |
| | processing | |
| 6 | Applications of Digital Signal Processing | 06 |
| | Correlation Functions and Power Spectra, Stationary Processes, Op- | |
| | timal filtering using | |
| | ARMA Model, Linear Mean-Square Estimation, Wiener Filter. | - |
| | TOTAL | |



Scheme & Syllabus

IV Year- VII & VIII Semester: B. Tech. (Electrical and Electronics Engineering)

| Tex | t/Reference Books |
|-----|--|
| 1 | S. K. Mitra, "Digital Signal Processing: A computer based approach", McGraw |
| | Hill, 2011. |
| 2 | A.V. Oppenheim and R. W. Schafer, "Discrete Time Signal Processing", Prentice |
| | Hall, 1989. |
| 3 | J. G. Proakis and D.G. Manolakis, "Digital Signal Processing: Principles, Algo- |
| | rithms And Applications", Prentice Hall, 1997. |
| 4 | L. R. Rabiner and B. Gold, "Theory and Application of Digital Signal |
| | Processing", Prentice Hall, 1992. |
| 5 | J. R. Johnson, "Introduction to Digital Signal Processing", Prentice Hall, 1992. |
| 6 | D. J. DeFatta, J. G. Lucas and W. S. Hodgkiss, "Digital Signal Processing", |
| | John Wiley & Sons, 1988. |



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IV Year- VII & VIII Semester: B. Tech. (Electrical and Electronics Engineering)

7EX5-12: DIGITAL CONTROL SYSTEM

Credit: 3 Max. Marks: 150(IA:30, ETE:120)
3L+0T+0P End Term Exam: 3 Hours

| 01. | Dit i Crim Exam. | , iiouis |
|-----|---|----------|
| SN | CONTENTS | Hours |
| 1 | Introduction: Objective, scope and outcome of the course. | 1 |
| 2 | Discrete Representation of Continuous Systems Basics of Digital Control Systems. Discrete representation of continuous systems. Sample and hold circuit. Mathematical Modelling of sample and hold circuit. Effects of Sampling and Quantization. Choice of sampling frequency. ZOH equivalent. | 05 |
| 3 | Discrete System Analysis Z-Transform and Inverse Z Transform for analyzing discrete time systems. Pulse Transfer function. Pulse transfer function of closed loop systems. Mapping from s-plane to z plane. Solution of Discrete time systems. Time response of discrete time system. | 06 |
| 4 | Stability of Discrete Time System Stability analysis by Jury test. Stability analysis using bilinear transformation. Design of digital control system with dead beat response. Practical issues with dead beat response design. | 06 |
| 5 | State Space Approach for discrete time systems State space models of discrete systems, State space analysis. Lyapunov Stability. Controllability, reach-ability, Reconstructibility and observability analysis. Effect of pole zero cancellation on the controllability & observability | 06 |
| 6 | Design of Digital Control System Design of Discrete PID Controller, Design of discrete state feedback controller. Design of set point tracker. Design of Discrete Observer for LTI System. Design of Discrete compensator. | 05 |
| 7 | Discrete output feedback control Design of discrete output feedback control. Fast output sampling (FOS) and periodic output feedback controller design for discrete time systems | 06 |
| | TOTAL | 36 |

| Text/Reference Books | | | | |
|----------------------|---|--|--|--|
| 1 | K. Ogata, "Digital Control Engineering", Prentice Hall, Englewood Cliffs, 1995. | | | |
| 2 | M. Gopal, "Digital Control Engineering", Wiley Eastern, 1988. | | | |
| 3 | G. F. Franklin, J. D. Powell and M. L. Workman, "Digital Control of Dynamic | | | |
| | Systems", Addison-Wesley, 1998. | | | |
| 4 | B.C. Kuo, "Digital Control System", Holt, Rinehart and Winston, 1980. | | | |



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7EX5-13: IMAGE PROCESSING AND PATTERN RECOGNITION

Credit: 3 Max. Marks: 150(IA:30, ETE:120)
3L+0T+0P End Term Exam: 3 Hours

| | End leim Exam. S | ilouis |
|----------|--|--------|
| SN | CONTENTS | Hours |
| 1 | Introduction: Objective, scope and outcome of the course. | 1 |
| 2 | Imaging in ultraviolet and visible band: Fundamental steps in image | 7 |
| | processing. Components inimage processing. Image perception in eye, | |
| | light and electromagnetic spectrum, Image sensing and acquisition using sensor array. | |
| 3 | Digital Image Fundamentals: Image sampling and quantization, | 8 |
| | Representing digital images, Spatial and gray-level resolution, Aliasing and Moire patterns, zooming and Shrinking digital images. | |
| 4 | Image Restoration: Image restoration model, Noise Models, Spatial and | 8 |
| - | frequency properties of noise, noise probability density functions. | 8 |
| | Noise - only spatial filter, Mean filter Statistic filter and adaptive filter, Frequency domain filters - Band reject filter, Band pass filter and Notch filter. | |
| 5 | Image Compression: Compression Fundamentals - Coding Redundancy, Interpixel redundancy, Psycho visual redundancy and Fidelity criteria. Image Compression models, Source encoder and decoder. | 8 |
| | Channel encoder and decoder, Lossy compression and compression | |
| | standards. Color space formats, scaling methodologies (like horizontal, vertical up/down scaling). Display format (VGA, NTSC, P AL). | |
| 6 | Expert System and Pattern Recognition: Use of computers in problem | 8 |
| | solving, information representation, searching, theorem proving, and pattern matching with substitution. | |
| | Methods for knowledge representation, searching, spatial, temporal and | |
| | common sense reasoning, and logic and probabilistic inferencing. Applications in expert systems and robotics. | |
| | TOTAL | |

| Tex | Text/Reference Books | | | | |
|-----|--|--|--|--|--|
| 1 | Rafael C. Gonzalez: Digital Image Processing, Pearson Education, Asia. 2009 | | | | |
| 2 | Vipula Singh: Digital Image Processing, Elesvier. 2013 | | | | |
| 3 | Nick Effard: Digital Image Processing, Pearson Education, Asia. 2000 | | | | |
| 4 | Jain A. K.: Digital Image Processing, Prentice Hall of India 1989 | | | | |
| 5 | Shinghal: Pattern Recognition- Techniques and Applications, Oxford. 2006 Jaya- | | | | |
| | raman: Digital Image Processing, TMH, 2011 | | | | |



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7EX4-21:DATA BASED MANAGEMENT SYSTEM LAB

Credit: 2 Max. Marks: 100(IA:60, ETE:40)

OL+OT+4P

| SN | Contents |
|----|--|
| 1 | Designing database and constraints using DDL statements. |
| 2 | Experiments for practicing SQL query execution on designed database. |
| 3 | Database connectivity using JDBC/ODBC. |
| 4 | Features of embedded SQL. |
| 5 | Designing front end in HLL and accessing data from backend database. |
| 6 | Designing simple projects using front end-back end programming. |
| 7 | Project for generating Electricity Bills |
| 8 | Project for managing student's attendance/marks details. |



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7EE4-22: Advanced Control System Lab

Credit: 2 Max. Marks: 100(IA:60, ETE:40)
0L+0T+4P

| SN | Contents |
|----|---|
| 1 | Determination of transfer functions of DC servomotor and AC servomotor. |
| 2 | Time domain response of rotary servo and Linear servo (first order and second |
| | order) systems using MATLAB/Simulink. |
| 3 | Simulate Speed and position control of DC Motor |

- Frequency response of small-motion, linearized model of industrial robot (first and second order) system using MATLAB.
- **5** Characteristics of PID controllers using MATLAB. Design and implementation of P, PI and PID Controllers for temperature and level control systems;
- **6** Design and implement closed loop control of DC Motor using MATLAB/Simulink and suitable hardware platform.
- 7 Implementation of digital controller using microcontroller;
- **8** Design and implementation of controller for practical systems inverted pendulum system.
- **9** To design and implement control action for maintaining a pendulum in the upright position (even when subjected to external disturbances) through LQR technique in an Arduino Mega.
- The fourth order, nonlinear and unstable real-time control system (Pendulum & Cart Control System)
- **11** Mini project on real life motion control system



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8EX4-01: DIGITAL COMMUNICATION AND INFORMATION THEORY

Credit: 3 Max. Marks: 150(IA:30, ETE:120)
3L+0T+0P End Term Exam: 3 Hours

| 3L | or or End Term Exam. |) IIUuIS |
|----|---|----------|
| SN | CONTENTS | Hours |
| 1 | Introduction: Objective, scope and outcome of the course. | 01 |
| 2 | PCM & DELTA Modulation Systems: PCM and delta modulation, quanti- | 08 |
| | zation noise in PCM and delta modulation. Signal-to-noise ratio in PCM | |
| | and delta modulation,T1 Carrier System, Comparison of PCM and DM. | |
| | Adaptive delta Modulation. Bit, word and frame synchronization, | |
| | Matched filter detection. | |
| 3 | Digital Modulation Techniques: Various techniques of phase shift, am- | 07 |
| | plitude shift and frequency shift keying. Minimum shift keying. Modula- | |
| | tion & Demodulation. | |
| 4 | Error Probability in Digital Modulation: Calculation of error probabili- | 08 |
| | ties for PSK, ASK, FSK & MSK techniques. | |
| 5 | Information Theory: Amount of Information, Average Information, Entropy, | 08 |
| | Information rate, Increase in Average information per bit by coding, Shannon's | |
| | Theorem and Shannon's bound | |
| | Capacity of a Gaussian Channel, BW-S/N trade off, Orthogonal signal | |
| | transmission. | |
| 6 | Coding: Coding of Information, Hamming code, Single Parity-Bit Code, | 08 |
| | Linear Block code, cyclic code &convolution code. | |
| | TOTAL | 40 |

| Text/Reference Books | |
|----------------------|--|
| 1 | Sklar: Digital Communication, Pearson Education. 2009 |
| 2 | R. N. Mutagi: Digital Communication, 2nd ed., Oxford. 2013 |
| 3 | P. Ramakrishna Rao: Communication Systems, MGH. 2013 |
| 4 | H. Taub & D.L. Schilling: Principles of Communication Systems, MGH. 2008 |
| 5 | Proakis: Digital Communication, MGH. 2008 |
| 6 | P. Chakrabarti: Principles of Digital Communications, Danpatrai & Sons. 1999 |
| 7 | K. Sam Shanmugam: Digital and Analog Communication System, John Wiley |
| | Sons. 2006 |
| 8 | Lathi, B. P.: Modern Digital & Analog Communication System, Oxford Press. 2009 |



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8EX4-21: EMBEDDED SYSTEM LAB

Credit: 1 Max. Marks: 50(IA:30, ETE:20)
0L+0T+2P

| SN | Contents |
|----|---|
| 1 | Introduction to Embedded Systems and their working. |
| 2 | Data transfer instructions using different addressing modes and block transfer. |
| 3 | Write a program for Arithmetic operations in binary and BCD-addition, subtraction, multiplication and division and display. |
| 4 | Interfacing D/A converter & Write a program for generation of simple waveforms such as triangular, ramp, Square etc. |
| 5 | Write a program to interfacing IR sensor to realize obstacle detector. |
| 6 | Write a program to implement temperature measurement and displaying the |
| | same on an LCD display. |
| 7 | Write a program for interfacing GAS sensor and perform GAS leakage detection. |
| 8 | Write a program to design the Traffic Light System and implement the same us- |
| | ing suitable hardware. |
| 9 | Write a program for interfacing finger print sensor. |
| 10 | Write a program for Master Slave Communication between using suitable hard- |
| | ware and using SPI |
| 11 | Write a program for variable frequency square wave generation using with suita- |
| | ble hardware. |
| 12 | Write a program to implement a PWM based speed controller for 12 V/24V DC |
| | Motor incorporating a suitable potentiometer to provide the set point. |